

BFO: a simple “brute-force” optimizer (yet another direct search algorithm)

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The problem

We consider the unconstrained nonlinear programming problem:

$$\text{minimize } f(x)$$

for $x \in \mathbb{R}^n$ and $f : \mathbb{R}^n \rightarrow \mathbb{R}$.

Important special case: the **nonlinear least-squares problem**

Additional constraints:

- there may be **bounds on the variables**
- derivatives are **unavailable**
- objective function possibly **nonsmooth**
- some variables can only assume **discrete values**

Motivation: parameter tuning in algorithm design (Audet-Orban), but many other examples. . .

Direct methods for optimization

A long history of **direct search methods**, including:

- Hookes-Jeeves, Nelder-Mead
- Coope-Price
- Dennis, Torczon, Lewis, Trosset (GPS)
- Dennis, Audet, Abramson (MADS).

This is one more of them

A **very simple** version:

BFO, a Brute-Force Optimizer

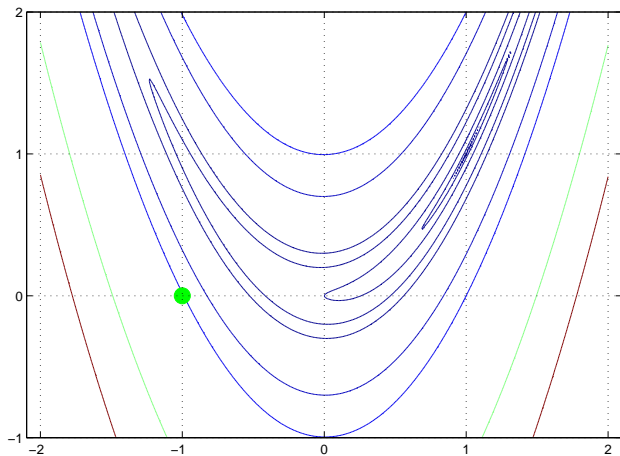
Main features: (not really original)

- Minimizes on progressively finer grids
- Some grid spacing remains fixed to user-specified discrete values
- Only for Local minimization...

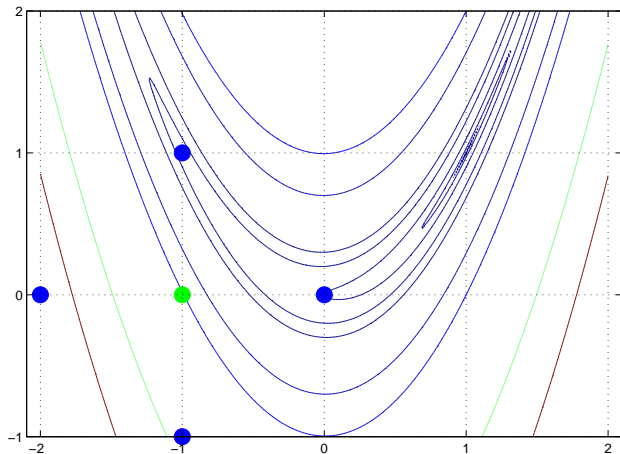
But also

- Attempts to learn from convergence history
- Includes some elements of random search
- User-friendly interface

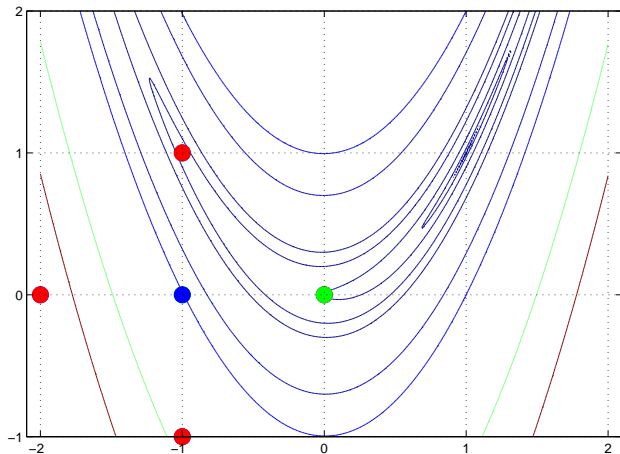
The compass-search on Rosenbrock's function



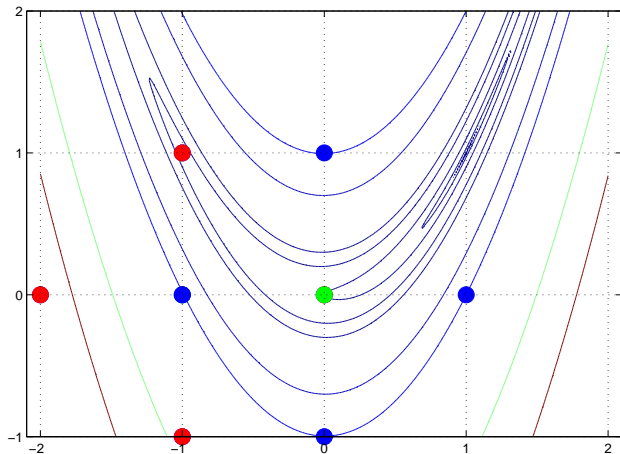
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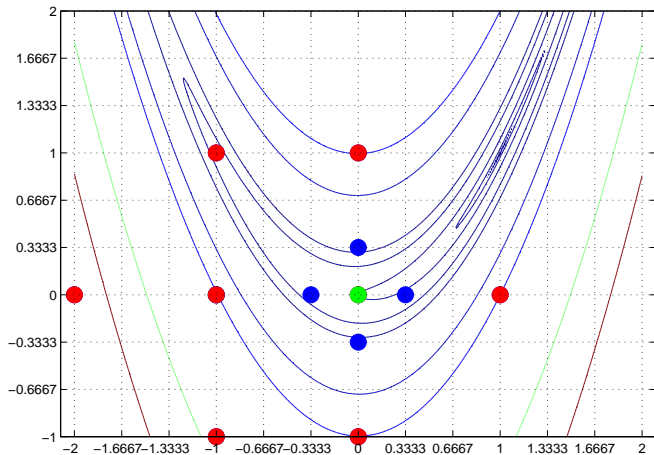
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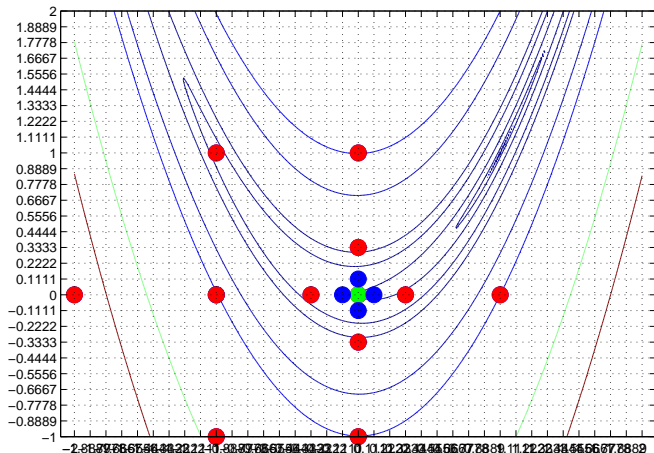
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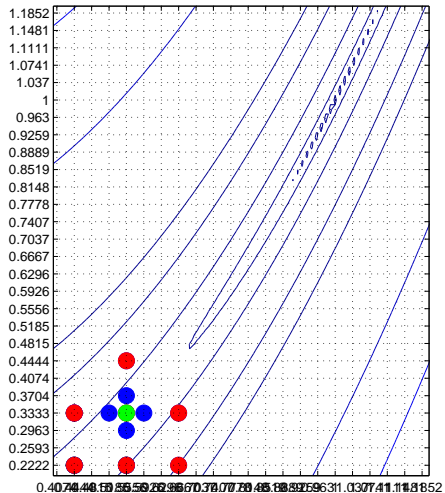
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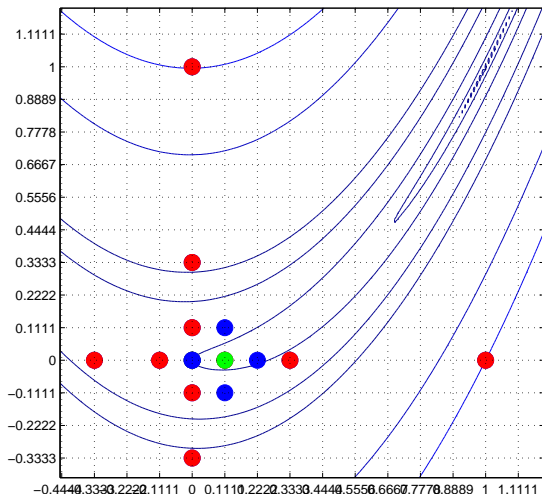
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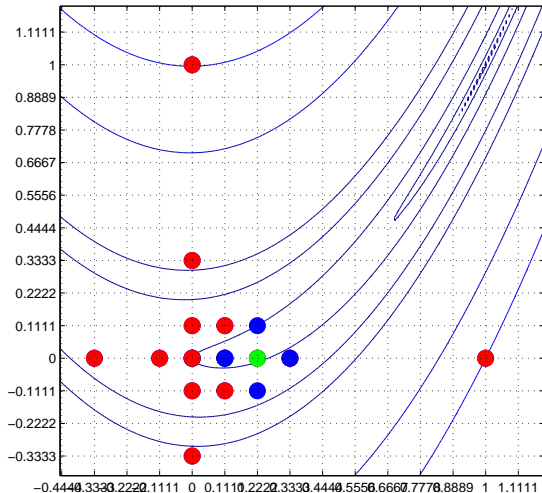
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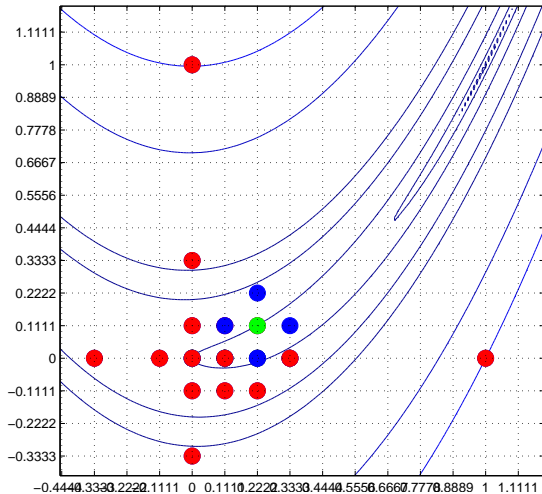
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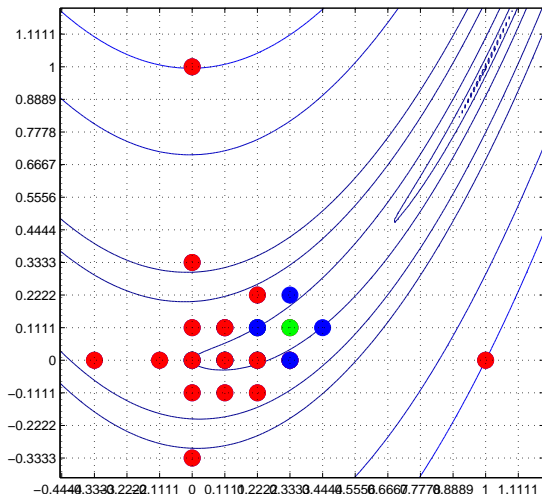
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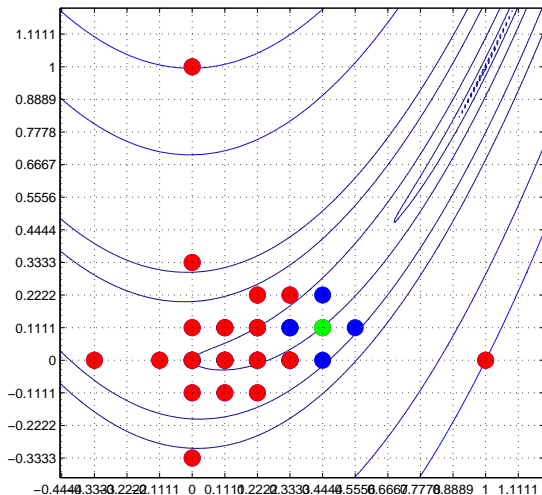
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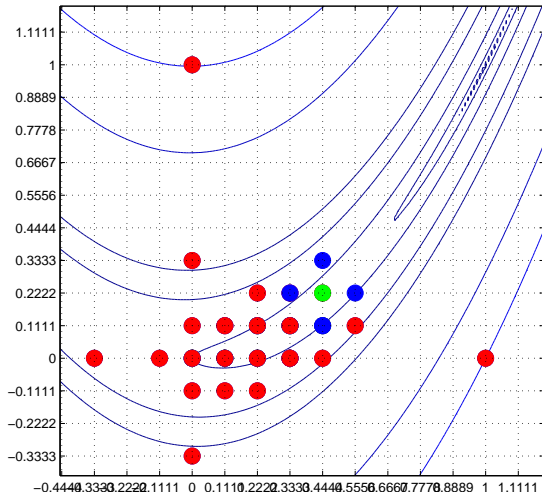
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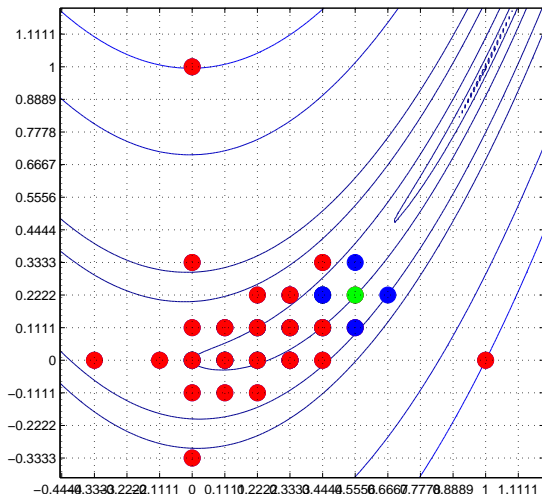
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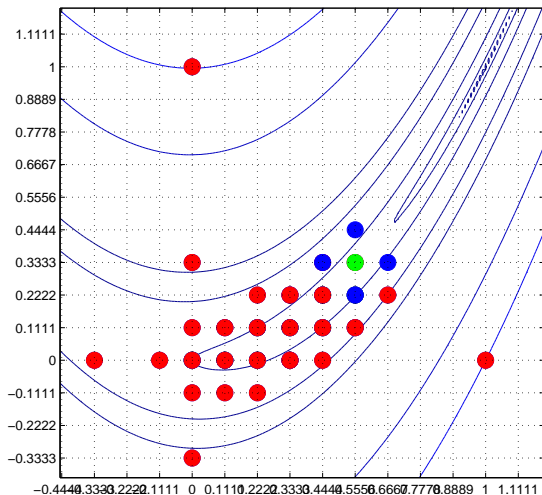
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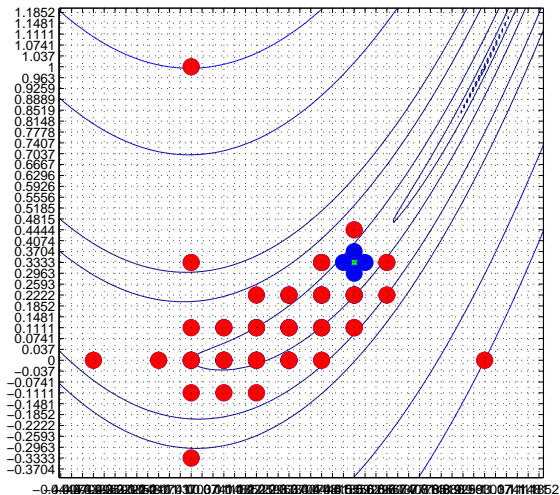
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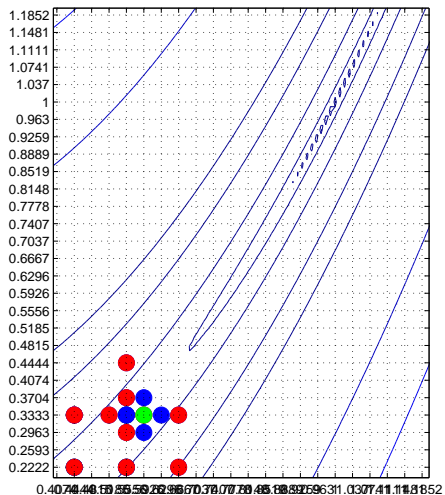
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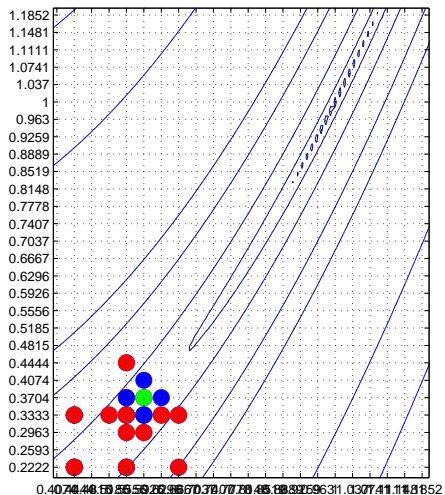
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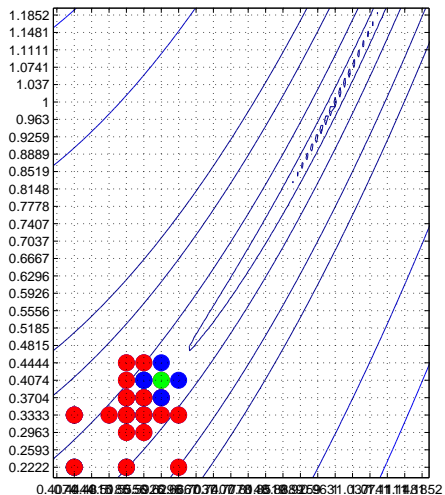
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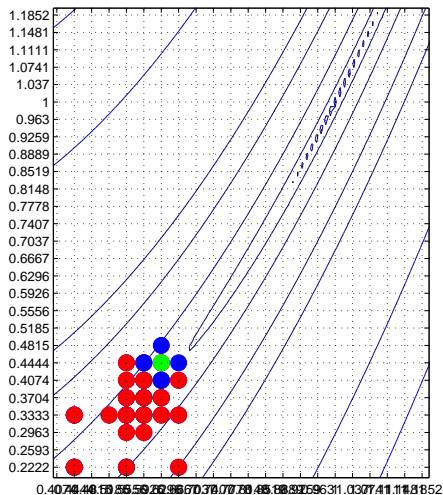
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Weaknesses and algorithmic “solutions” (1)

- All compass points evaluated at each iteration
 - stop evaluating as soon as **sufficient reduction** is obtained
- Painful zigzag crawling when axis not suitable
 - align axis on a grid with **progress direction** on previous grid (+ **random** complement)
 - define progress on a user-defined number of past iterations (**inertia**)
- Compute function at infeasible points
 - keep track of **active** and **nearly-active** bound constraints

Weaknesses and algorithmic “solutions” (2)

- Slow progress on fine grids
 - expand the (continuous) grid on “successful iterations”
- Minima in neighbouring discrete subspaces not close to each other
 - recursively explore a depth-first tree of discrete subspaces
 - keep track of record value in each such subspace to avoid re-exploration

BFO: the Brute-Force Optimizer

User may specify (amongst others):

- grid shrinking/expansion **factors**
- **inertia** for defining progress directions
- **initial scale** in continuous variables

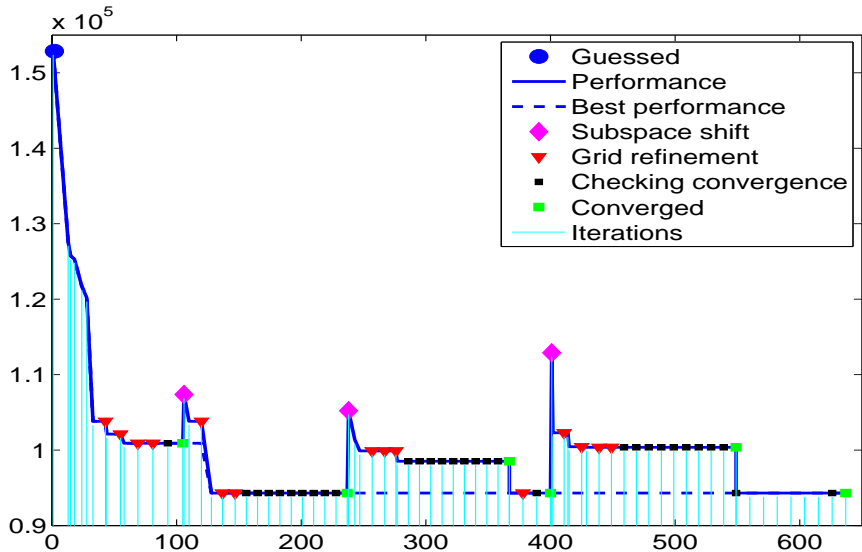
How to choose suitable defaults?

Use BFO!

The setting for algorithm tuning

- a set of 54 [test problems](#)
- define objective function value = total number of evaluation to solve all problems
- choose (reasonable) initial default values
- ... let BFO optimize for finding better values!
(problem in 5 continuous and 1 discrete variables)

637 iterations of performance optimization



Implementation features:

- **check-pointing** at user-specified frequency
- norms of **vector functions** $t(f(x))$
- allows objective **functions with user-defined parameters**
- allows **partial objective computations**
- allows **randomized termination test**
- provides a FD estimate of the (projected) gradient's norm (in the continuous variables) at termination
- very **flexible** keyword-based **calling sequence**

- yet another **direct method** for mixed integer local optimization
- simple compact implementation
- freely-available easy-to-use **Matlab** package **BFO**
- useable for **algorithm tuning**
 - used on other codes (DFO, ...)
 - beware of overfitting!
- more to do (constraints, use of structure, ...)

Thank you for your attention!