

BFO: a simple “brute-force” optimizer and its self optimization

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The problem

We consider the unconstrained nonlinear programming problem:

$$\text{minimize } f(x)$$

for $x \in \mathbb{R}^n$ and $f : \mathbb{R}^n \rightarrow \mathbb{R}$.

Important special case: the **nonlinear least-squares problem**

Additional constraints:

- there may be **bounds on the variables**
- derivatives are **unavailable**
- objective function possibly **nonsmooth**
- some variables can only assume **discrete values**

Motivation: parameter tuning in algorithm design (Audet-Orban), but many other examples. . .

Direct methods for optimization

A long history of **direct search methods**, including:

- Hookes-Jeeves, Nelder-Mead
- Coope-Price
- Dennis, Torczon, Lewis, Trosset (GPS)
- Dennis, Audet, Abramson (MADS).

This is one more of them

A **very simple** version:

BFO, a Brute-Force Optimizer

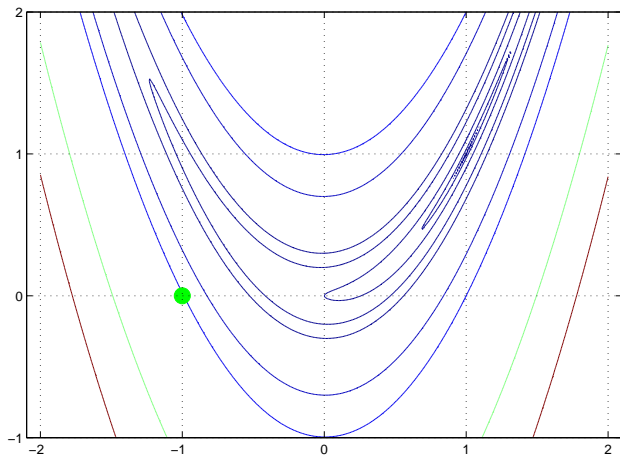
Main features: (not really original)

- Minimizes on progressively finer grids
- Some grid spacing remains fixed to user-specified discrete values
- Only for Local minimization...

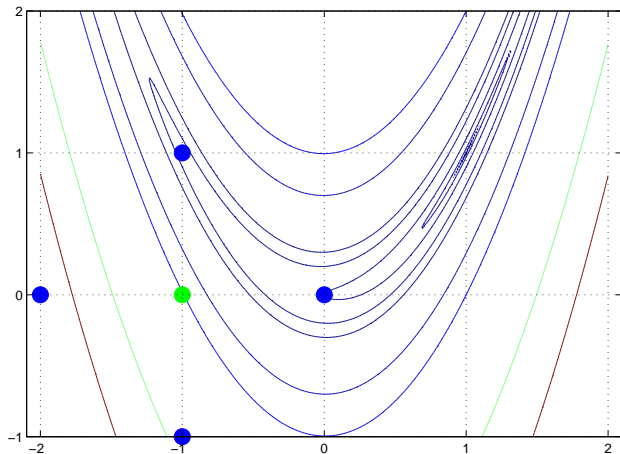
But also

- Attempts to learn from convergence history
- Includes some elements of random search
- User-friendly interface

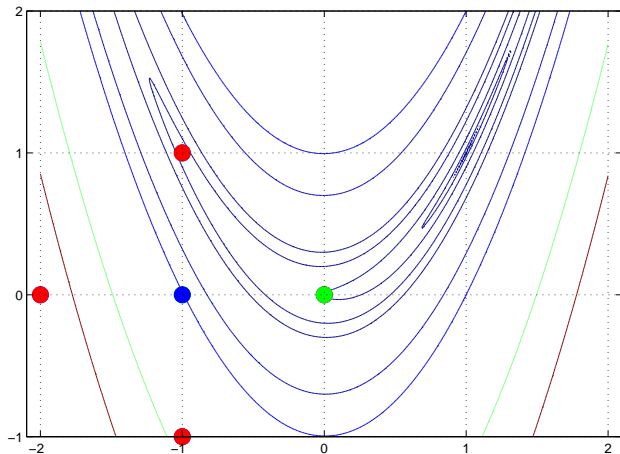
The compass-search on Rosenbrock's function



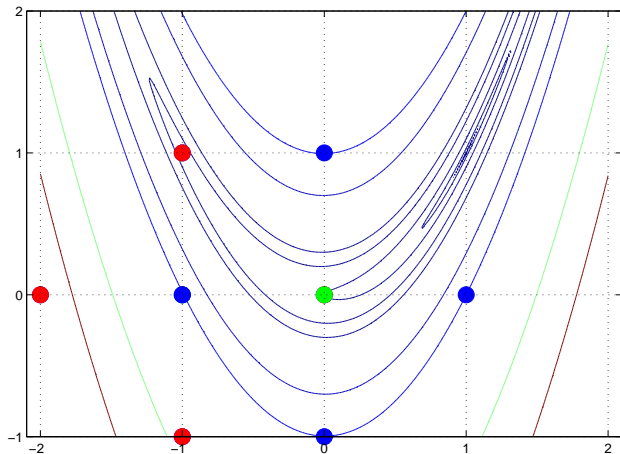
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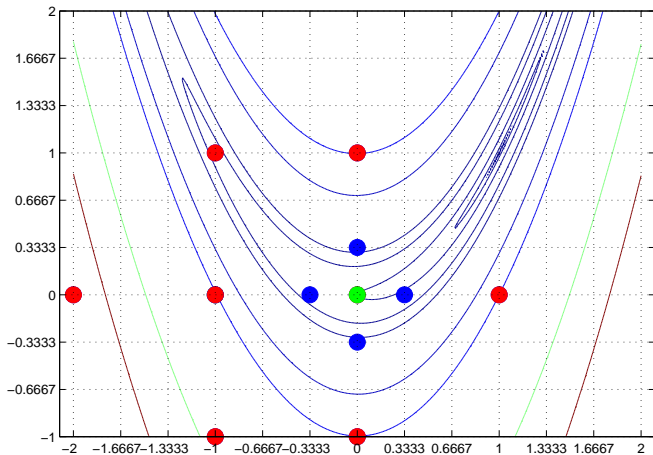
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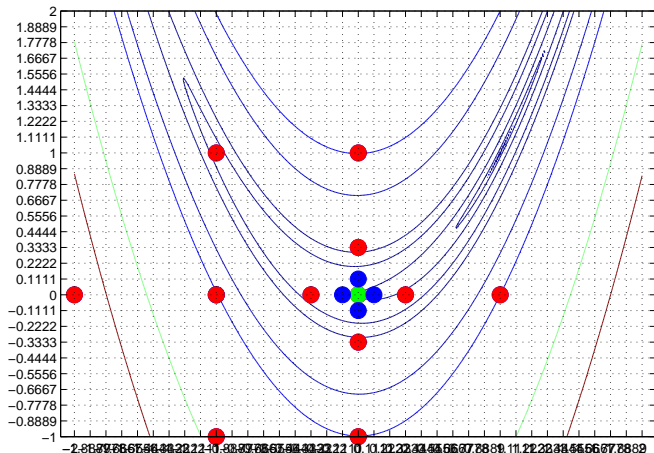
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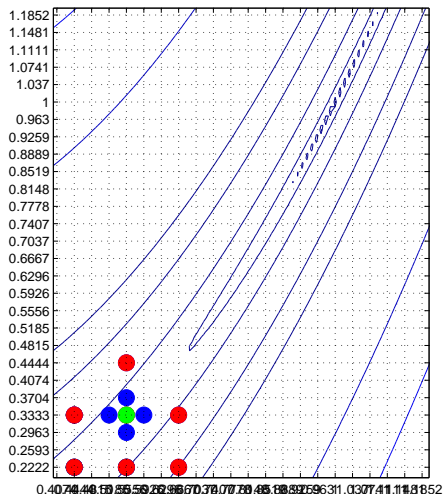
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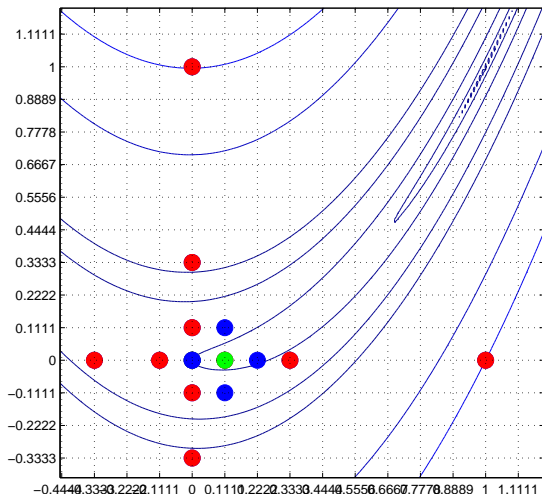
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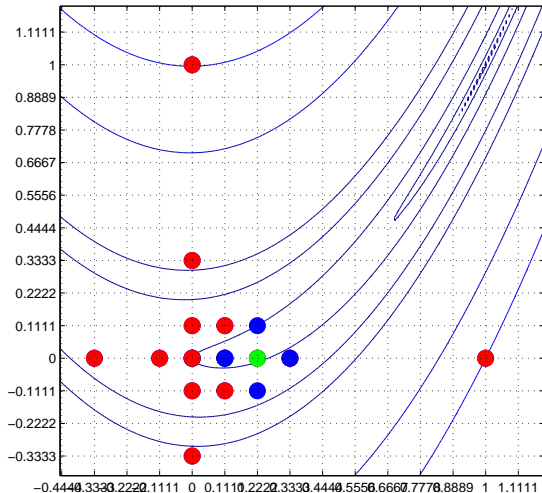
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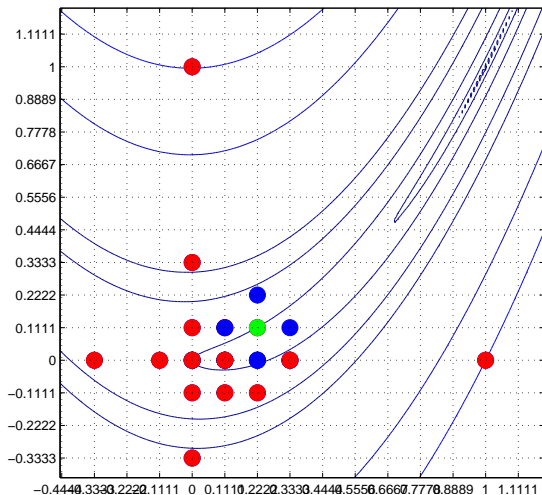
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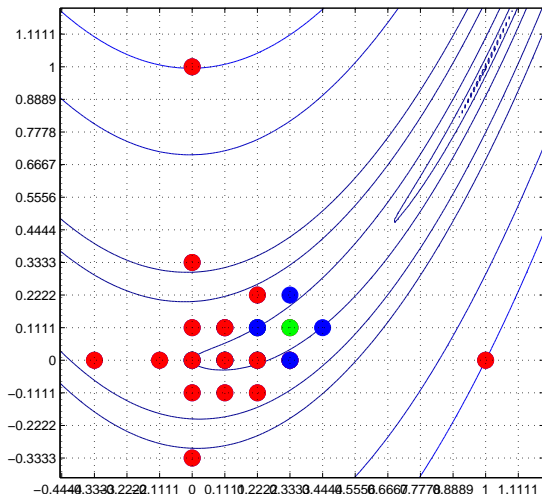
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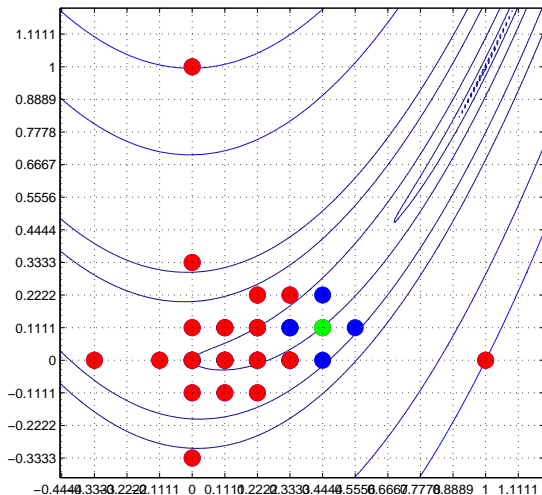
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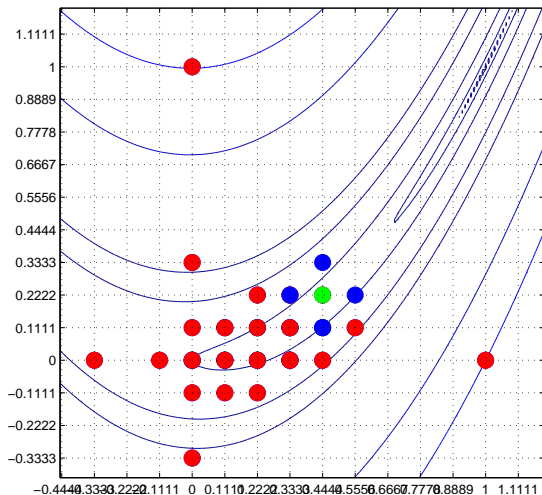
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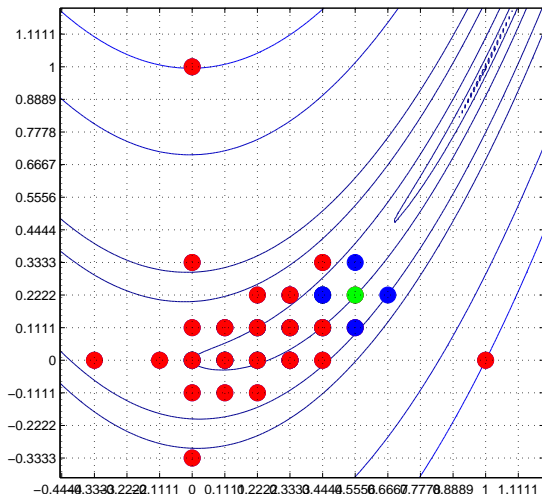
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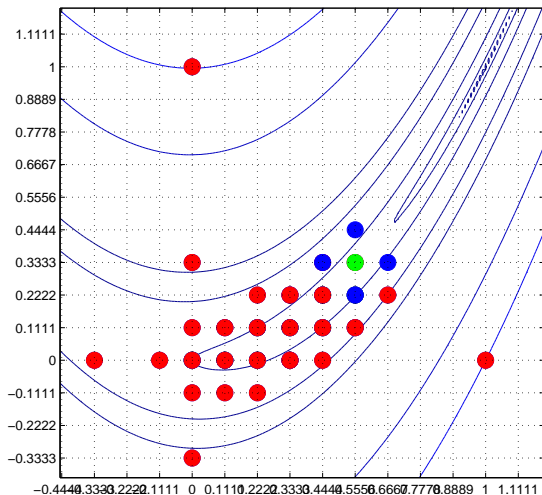
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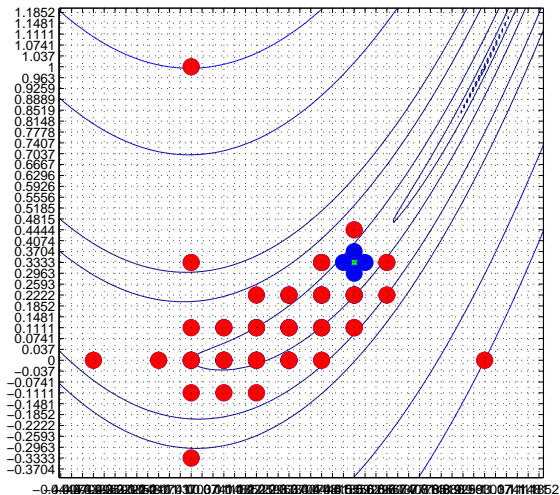
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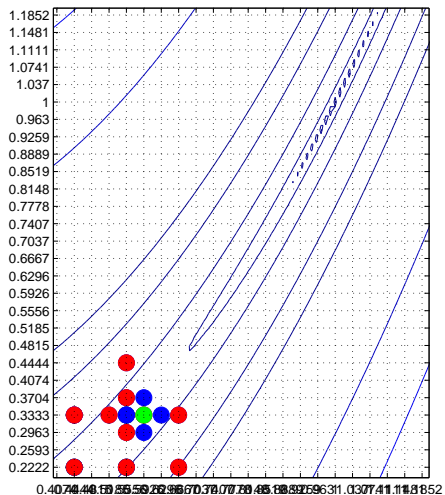
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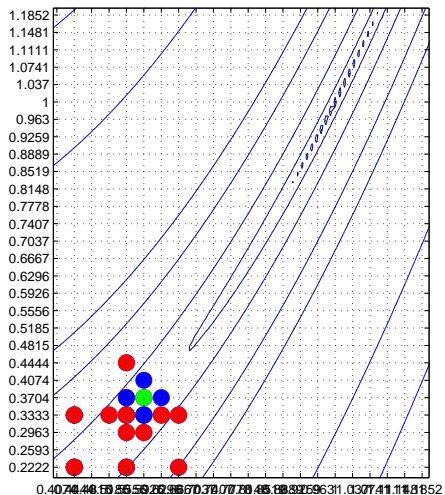
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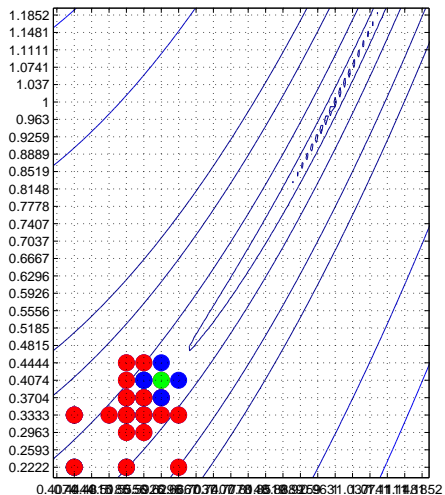
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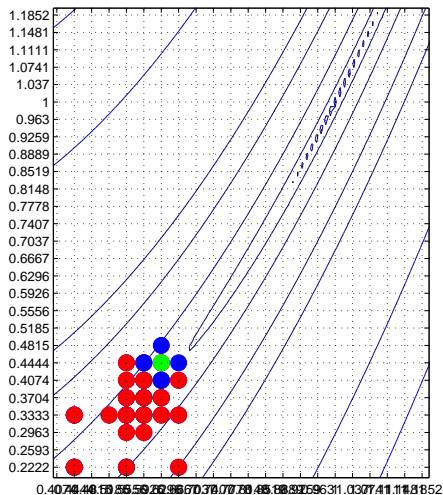
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Weaknesses and algorithmic “solutions” (1)

- All compass points evaluated at each iteration
 - stop evaluating as soon as **sufficient reduction** is obtained
 - (suitable ordering of search directions)
- Painful zigzag crawling when axis not suitable
 - align axis on a grid with **progress direction** on previous grid (+ **random** complement)
 - define progress on a user-defined number of past iterations (**inertia**)
 - (independent scale for each variable)

Weaknesses and algorithmic “solutions” (2)

- Compute function at infeasible points
 - keep track of **active** and **nearly-active** bound constraints
- Slow progress on fine grids
 - **expand the** (continuous) **grid** on “successful iterations”
- Minima in neighbouring discrete subspaces not close to each other
 - recursively explore a **local tree** of discrete subspaces
 - keep track of **record value** in each such subspace to avoid re-exploration

Implementation features:

- **check-pointing** at user-specified frequency
- norms of **vector functions** $t(f(x))$
- allows objective **functions with user-defined parameters**
- allows **partial objective computations**
- allows **randomized termination test**
- provides a FD estimate of the (projected) gradient's norm (in the continuous variables) at termination
- very **flexible** keyword-based **calling sequence**

BFO: the Brute-Force Optimizer

User may specify (amongst others):

- grid shrinking/expansion **factors**
- **inertia** for defining progress directions
- **initial scale** in continuous variables
- local **tree-search** strategy (depth-first vs breadth-first)
- **max conditioning** for sampling gradient descent

How best choose the algorithmic parameters?

- a set of 64 (uncs) + 64 (box) + 47 (mixed) **test problems**
- define objective function value
 $\phi_{BFO}(\text{params}) =$ total number of evaluations to solve all problems
- choose (reasonable) initial default values
- **simple idea**: let BFO optimize for finding better values!
(problem in **6 continuous** and **2 discrete variables**)

(D. Orban and Ch. Audet)

A robust approach (1)

DANGER: overfitting. . .

Investigate other formulations inspired by **robust optimization**
(in continuous variables)

(Idea also considered by [A. Conn?](#))

- local sample $\mathcal{S}(\text{params})$:

Consider varying each continuous algorithmic parameter by

−5% −1% 0% +1% +5%

around **each tested value** (percentage tunable)

- local box

$$\mathcal{B}(\text{params}) = \prod_1^{\#\text{params}} [0.95 \text{ params}_i, 1.05 \text{ params}_i]$$

A robust approach (2)

Three “robust” formulations:

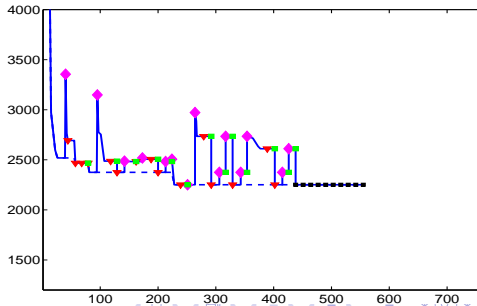
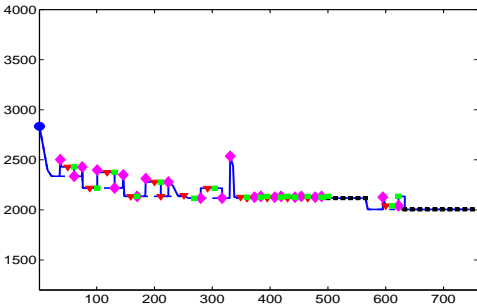
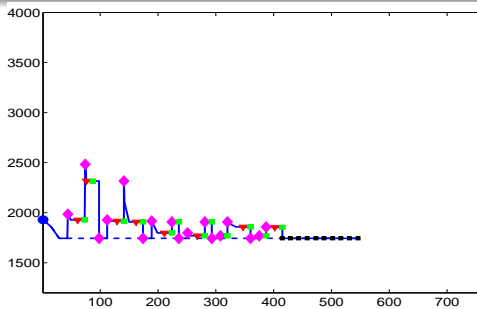
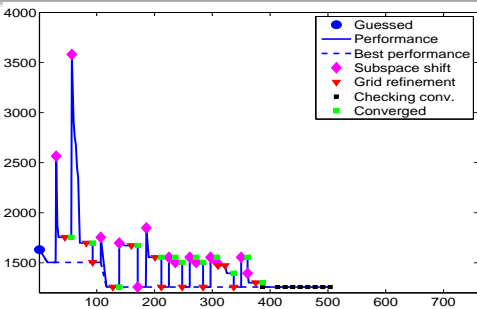
$$\min_{\text{params}} \sum_{\text{pars} \in \mathcal{S}(\text{params})} \phi_{BFO}(\text{pars})$$

$$\min_{\text{params}} \max_{\text{pars} \in \mathcal{S}(\text{params})} \phi_{BFO}(\text{pars})$$

$$\min_{\text{params}} \max_{\text{pars} \in \mathcal{B}(\text{params})} \phi_{BFO}(\text{pars})$$

- progressively (and considerably) **more expansive**
- BFO may be used for **both optimization levels** (form. 2 & 3)
- maximization problem possibly approximate (moderately **coarse** stopping rule)

On 3 test problems only: the optimization history



On 3 test problems only: the optimal parameters

	shrink	decr.	max exp.	in.	scale	exp.	conclim
guess	0.1	0.00001	3	5	1	2.1	1.2
simple	0.05	0.56469	3	6	1	2.1	1.147526
sum	0.1	0.00001	3.200578	5	1.25	2.114963	1.0734592
max (\mathcal{S})	0.05	0.00001	4.0626793	9	1.1787	1.99772	1.4533078
max (\mathcal{B})	0.1	0.000001	3.258	6	1.25	2.1	1.2

Which is the most sensible?

Maybe max (\mathcal{B}) ?

More computations are on the way...

Conclusions

BFO

- yet another **direct method for mixed integer local optimization**
- further direct improvements under development (ordering, sample gradients, etc)
- simple compact implementation
- freely-available easy-to-use **Matlab** package
- useable for algorithm **tuning**
- more to do (constraints, use of structure, ...)

Optimization of algorithmic parameters

- four **formulations** proposed and (nearly) tested
- **fully robust** formulation most reasonable?

Thank you for your attention!